## INTEGRAL UNIVERSITY, LUCKNOW B.TECH. V SEMESTER AUTOMATIC CONTROL SYSTEM (IEC-504) QUIZ-01 (2014-2015)

- 1. The transfer function is defined only for \_\_\_\_\_\_ systems.
- 2. The transfer function is independent of the \_\_\_\_\_\_ to the system.
- 3. The transfer function is defined as the ratio of the \_\_\_\_\_\_ to the \_\_\_\_\_\_ with the assumption that all \_\_\_\_\_\_ are zero.
- 4. The transfer function is said to be \_\_\_\_\_\_ if the order of the denominator polynomial is greater than that of the numerator polynomial.
- 5. The transfer function is said to be \_\_\_\_\_\_ if the order of the numerator polynomial is equal to that of the denominator polynomial.
- 6. The transfer function is said to be \_\_\_\_\_\_ if the order of the numerator polynomial is is greater than that of the denominator polynomial.
- 7. The characteristic equation of a linear system is defined as the equation by setting the \_\_\_\_\_\_ of the \_\_\_\_\_\_ to zero.
- 8. The transfer function obtained by replacing s with  $j\omega$  in the original transfer function is called the
- 10. Systems whose differential equations are identical are called \_\_\_\_\_\_\_ systems.

Ref.: Control Systems by A. Anand Kumar, PHI